

Camouflage Technique Based Multifunctional Army Robot

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Abstract: Science is a fast-paced area evolving, producing the technologies that will make life easier for human beings. ROBOT is one such invention. Robot means a computer programmable for performing complex series of acts. Military activities are considered the most hazardous area in which to operate. Together with other applications such as online surveillance, land mine detection, the camouflage robot is the solution to reduce loss of human life by replacing it during such operations. The proposed framework comprises of observation camera, disguise RGB's, and metal item identifying PIR sensor. Through this camera the robot detects the shade of the encompassing zone and changes its shading to mix.

Keywords: Camera; Camouflage; Colour Sensor; Wireless Robot; RGB, ZigBee; PIR sensor; Wi-Fi Module

I. INTRODUCTION

The earlier idea of Automatic Gun focusing on framework is to utilize mechanization to distinguish and focus on the living item or any development in exceptionally made sure about territories, for example, Border. Mechanization is a computerized weapon focusing on framework for the sensor base which focuses on the living article inside the sensor go. Programmed focusing of cylinders is basically founded on PIR sensors, microcontroller and RF transmitting and getting unit with focusing on weapon. Up to that point, Iron Spike wires outskirts, and a watchtower from which an individual ceaselessly flashes the light day and night over the fringe zone. Those individuals are completely answerable for security at outskirts. Programmed Gun Targeting System won't expel full obligation from its fighters yet will share greatest duty and diminish human blunder at the outskirts. The sensors will have the option to identify any living element inside the range given. The sensor signal is conveyed to raspberry, the code is produced and that code

is transmitted by means of RF transmitter to the watch tower where the code is gotten by the RF recipient. The collector side control microcontroller focusing on firearm, signal and engine driver circuit as indicated by the got code and focusing on weapon at the beneficiary will focus on the living article. The ringer will show that sensor detects target. Along these lines the individual on the watch tower can decipher the article's area without any problem. The computerized firearm focusing on program can utilize computerization to improve fringe safeguard, which can diminish human endeavors to huge degree. With the assistance of face acknowledgment and Bluetooth innovation, the framework can be additionally actualized later on so the framework will work all the more productively. The point is to actualize framework for a given face, and furthermore recognize it from countless appearances put away, with some continuous varieties. It gives us an effective method to discover the space underneath the measurements. Furthermore, this calculation can be stretched out to perceive an individual's sexual orientation or decipher an individual's outward appearance. This framework comprises of a portable, Internet-controlled robot that has camera mounted and a PIR sensor to identify living bodies. Clients will have the option to control the robot by means of web, along these lines giving robot remote control.

II. LITERATURE SURVEY

A. Paper Title: Camouflage color changing robot

Authors: Hitesh Shinde, Kirti Sonawane, Pranit Rane, Atharva Pathak and Sumita Chandak Atharva

Science is a fast-paced area evolving, producing the technologies that will make life easier for humans. One such technology innovation is ROBOT. The word robot implies a machine programmable for doing complex arrangement of activities. Military activities are considered the most hazardous area in which to operate. The camouflage robot is the solution used in such operations to



reduce the loss of human life by replacing it. The system proposed consists of one surveillance camera & one color sensing camera. Via this camera, the robot senses the ambient color & changes its color to blend in with it. This makes the enemy's unaided eyes hard to spot. The robot can be controlled remotely using a computer to establish the connection between them.

B. Paper Title: Comparison of Matching Techniques

Authors: N Jayanthi and S Indu

Each picture is characterized by its one of a kind arrangement of qualities. These highlights are selective to each picture, and subsequently help to recognize and segregate between pictures later on. Features might be characterized as the object of intrigue or a "fascinating" some portion of a picture, utilized as a beginning stage for certain PC vision computations. Since segments are utilized as the underlying stage and fundamental hypothesis for coming about calculations, the general calculation should normally be in a similar class as its finder of highlights. The charming property for a component finder is in this way rehash capacity: independent of whether a similar element is found in at least two separate pictures from a similar scene. Distinguishing proof of highlights is an action that procedures pictures at low rates. That is, it is regularly proceeded as the fundamental procedure on an image, and investigates every pixel to check whether a part is available at that pixel. In the event that this is a piece of a bigger calculation, at that point the computation must check the image intermittently in the highlights spot. In PC vision and picture preparing highlight distinguishing proof implies methods for making sense of picture information considerations and choosing close by decisions at each image point whether there is a picture highlight of a given animal types around then .

C. Paper Title: Design and Implementation of e-Surveillance Robot for Video Monitoring and Living Body Detection

Authors: Dr. Shantanu k Dixit and S B Dhayagonde

At the point when an individual enters an observed zone, PIR movement finders are regularly utilized related to different pieces of the fighting field in executing automated framework. At the point when somebody enters made sure about spots, they will promptly send a sign by means of remote correspondence to the control room segment and are shown by caution to the control room. In the host zone, the individuals concerned ought to comprehend that an outcome has happened. Simultaneously, the microcontroller-associated web camera continues catching what's happening there at the host spot and sparing it into the PC. At the point when security individuals in the administrative room get a caution sign to the host area, they sign in by means of web to the host segment PC and view PC recordings of all fighting segment data.

D. Paper Title: Implementation of Spy Robot for A Surveillance System using Internet Protocol of Raspberry Pi

Authors: Ghanem Osman Elhaj Abdalla and T Veeramanikandasamy

In this paper, we alluded to the PIR sensor which is utilized to distinguish live articles (by identifying the degree of IR radiation) and which is most appropriate for checking. This paper derived fixing a camera on the robot. In this the government agent robot is worked with Raspberry Pi, We are utilizing this equipment since it is easy to actualize sensor and camera activity. It additionally alludes to robot working in uneven territory and delicate territories. It likewise assists with keeping up social control, perceive and screen dangers and is helpful to governments and law implementation to forestall or examine live observation of crime. In the security framework, the camera mounted on a robot goes about as a security patroller which can screen territories that cannot be gotten to by people. We can forestall loss of human life by utilizing observation robot. The robot can go toward any path. Utilizing Wi-Fi medium it tends to be worked remotely.

E. Paper Title: Current and Future Trends in Sensor Networks

Authors: Mokhtar Aboelaze, and Fadi Aloul

Late advancements in VLSI innovation and MEMS (Micro-Electro-Mechanical Systems) just as remote correspondence innovation have permitted sensor systems to be fabricated where enormous quantities of extremely little hubs are spread over specific situations to be detected and answered to a focal hub (client). There are numerous applications in Sensor systems. In the military, they are utilized for observing front lines, and following articles. Notwithstanding the production lines and stockrooms for following and checking, they are utilized for seismic information assortment and announcing.

III. METHODOLOGY

A. Hardware

a) Transmitter side:

Transmitter side has robot and screen control over live machine status and video captured by robot-installed camera. Wireless transmission of the data is achieved using Wi-Fi module.

b) Receiver side:

Camera and motors can be operated by the receiver side user using motor driver. The metal sensor readings are received continuously through the Wi-Fi module at the user's end. Using colour sensors, the colour is sensed and a proportional value is fed using the Raspberry Pi to the led strip.



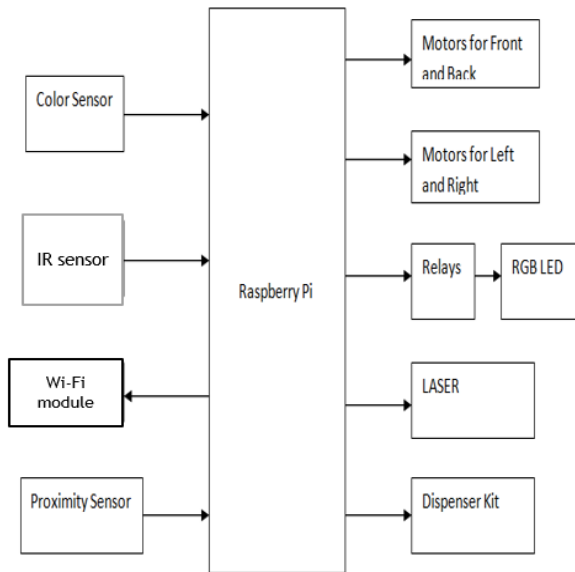


Fig 1. Sensors Connected to Raspberry Pi

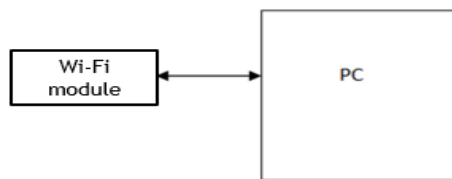


Fig 2. Controlling Through PC

B. Software

a) Linux

Linux is the most generally utilized and most popular open source working framework. As a working framework, Linux is programming that lives on a gadget under the various applications, acknowledges demands from different projects and transfers these solicitations to the equipment of the machine.

b) Python

Python is a programming language of high standard designed to be easy to read and simple to implement. It is open source, meaning it can be used freely, even for commercial applications. This is considered a structured language and is mostly used to construct interactive web content and web applications.

IV. RESULT AND ANALYSIS

A. Camouflage Feature of Robot

The RGB's are mounted on the robot chassis. Based on the 8-bit value the color of the RGB received is changed and the color of the robot is adjusted to the surrounding.

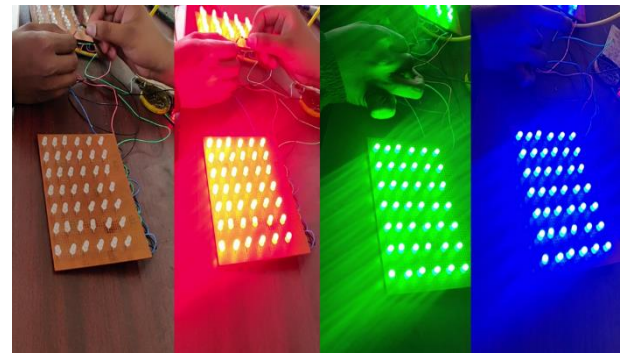
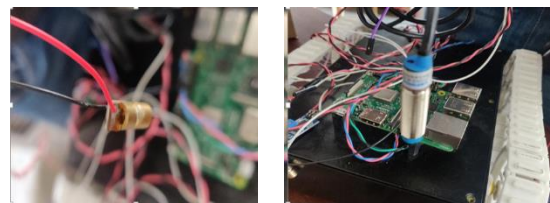


Fig 3. RGB's

B. Laser Dot and Landmine detection

Utilized for execution of Laser Guns. Voltage to work: 5V DC. Laser yield: 5mV. At the point when an object methodologies the attractive field, electromagnetic acceptance actuates an enlistment current (whirlpool current) to circle inside the objective. The enlistment current stream increments as the objective methodologies the sensor, which causes the heap on the wavering circuit to rise.



(a) (b)

Fig 4. (a) LED Trigger and (b) Proximity sensor

V. FUTURE SCOPE

The fundamental motivation behind the undertaking is to run a robot utilizing PC. The machine to identify the metallic nearness additionally, and the PIR sensor recognizes any human nearness in its manner, and if any human nearness is identified, it forestalls an alert framework and signals. The smaller scale controller is modified so that the robot moves brilliantly relying upon the squeezed key, and it distinguishes the nearness of metallic articles in mines and cautions by means of bell alert framework with the assistance of the metal location sensor. This current undertaking's downside is that robot status isn't known. This can be evacuated by getting a GSM module that gives robot working status. By adding remote camera to the robot, just utilizing GPRS and GPS would one be able to see the outside world from our PC.

By associating the temperature sensor to the robot one can get the temperature of risky territories on the PC itself as opposed to sending individuals there and confronting issues on the ground we can send the robot there and the sensor recognizes the temperature and gives the microcontroller data and the microcontroller furnishes the handset with the data from which we can acquire the

information on the pc side. By interfacing the smoke sensor to the robot, the data identified with smoke or gas fixation can be gotten in the particular field, for example (coal mineshafts, risky zones, and so forth). Sensor detects the data and offers it to the small scale controller and offers it to the handset and from that we get the data on the PC. By associating the separate instruments to the robot, it tends to be utilized for cultivating purposes in horticulture. This robot can go ahead and in reverse just as left and right contingent upon our headings so we can just utilize robot to do some piece of horticulture from pc. We can shoot the objective from pc by connecting the terminating instrument and remote camera to the robot. Here we can see the contrary objective by utilizing the camera and you can shoot the objective from your PC by squeezing the chose button so you can undoubtedly oversee circumstances like the Mumbai psychological oppressor assault without loss of human life and we can likewise the our officers' exertion.

VI. CONCLUSION

The proposed framework is a substitution to human life. This proposed robot assists with going about as a security framework and furthermore as a lifeline as human life is in every case more organized. It establishes and assumes a significant job in watching out for the fields of war and catching the environmental factors. Since it depends on the changing impact of the Chameleons shading, the robot changes its shading relying upon the general condition and is avoided the knowledge of the adversary. Robot to robot contact makes out of inclusion territory administration. The covering highlight additionally makes it hard to identify the robot through the bare natural eye. Accordingly, in the entirety of the proposed framework gives our security powers some assistance in identifying interlopers. The robot can likewise be utilized in spots of high height where people can't live.

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